## Stolen Base Physics

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Few plays in baseball are as consistently close and exciting as the stolen base. ${ }^{1}$ While there are several studies of sprinting, ${ }^{2-4}$ the art of base stealing is much more nuanced. This article describes the motion of the basestealing runner using a very basic kinematic model. The model will be compared to some data from a Major League game. The predictions of the model show consistency with the skills needed for effective base stealing.

## The basic kinematic model

Let's just consider a steal of second base as opposed to third or home. The goal of the runner is to minimize the time required to get there. The basic kinematic model breaks the total distance between the bases ( $D=90.0 \mathrm{ft}$ ) into four parts.

1. The lead off - the distance $d_{\mathrm{L}}$ away from first base where the steal attempt begins.
2. The jump - the distance $d_{\mathrm{j}}$ while accelerating at a constant rate of $a_{+}$away from first base when starting from rest.
3. The run - the distance $d_{\mathrm{r}}$ while traveling at a constant top speed $v$.
4. The slide - the distance $d_{s}$ while decelerating from top speed at a constant rate of $a_{-}$into second base at a velocity of $v_{\mathrm{f}}$.
In summary, the model assumes the velocity-versus-time graph shown in Fig. 1, resulting in the distance-versus-time graph of Fig. 2. The total distance between the bases is just the sum of the four distances described above,

$$
\begin{equation*}
D=d_{\mathrm{L}}+d_{\mathrm{j}}+d_{\mathrm{r}}+d_{\mathrm{s}} \tag{1}
\end{equation*}
$$

We can use the kinematic equations to express the jump distance and the time for the jump in terms of the top speed $v$ and the acceleration $a_{+}$,

$$
\begin{equation*}
d_{\mathrm{j}}=\frac{v^{2}}{2 a_{+}} \text {and } t_{\mathrm{j}}=\frac{v}{a_{+}} \tag{2}
\end{equation*}
$$

Similarly, for the slide distance but including the final speed,

$$
\begin{equation*}
d_{\mathrm{s}}=\frac{v^{2}-v_{\mathrm{f}}^{2}}{2 a_{-}} \text {and } t_{\mathrm{s}}=\frac{v-v_{\mathrm{f}}}{a_{-}} \tag{3}
\end{equation*}
$$

The run distance needs to be expressed in terms of the total distance while the run time is just the distance over the velocity,

$$
\begin{align*}
& d_{\mathrm{r}}=D-d_{\mathrm{L}}-d_{\mathrm{j}}-d_{\mathrm{s}} \text { and } \\
& t_{\mathrm{r}}=\frac{d_{\mathrm{r}}}{v}=\frac{D-d_{\mathrm{L}}-d_{\mathrm{j}}-d_{\mathrm{s}}}{v} \tag{4}
\end{align*}
$$



Fig. 4. The position vs time for the Crawford stolen base. The red line is a fit based on the kinematic model.


Fig. 5. The velocity vs time for the Crawford stolen base. The red line is a fit based on the kinematic model.

Equation (6) is anything but transparent. However, we'll address the importance of each parameter in a bit after we get some typical data from an actual Major League stolen base.

## Some actual data

Getting position-versus-time data for a stolen base should be relatively easy. Just find some video, use the 90 feet between the bases as a scale, measure the position of the runner frame by frame, and you're done. Not so fast! If you watch a game on TV you will rarely find a shot that watches the runner from beginning to end. If you do, it is very likely that the camera either moves or zooms during the play. This destroys the scaling. So, professional video of a game is rarely helpful.

This is where YouTube, a fan in the cheap seats, and baseball history all come together for the benefit of physics. The record for stolen bases in a single Major League game is six. On May 3, 2009, Carl Crawford of the Tampa Bay Rays had
already stolen five when he reached first in the eighth inning. A fan in the top deck high above the third-base line expectantly turned on a video camera hoping to capture the historic moment when the record would be tied. Crawford indeed stole second. ${ }^{5}$ Our unnamed but nonetheless beloved fan posted the video on YouTube. ${ }^{6}$ Figure 3 is an image from that video.

Figure 4 is a plot of position versus time for the Crawford stolen base data. The blue diamonds are the data points.
The red line has the same shape as Fig. 2 because it is a leastsquares fit to this data using the kinematic model. The values of the parameters for this fit are:

$$
\begin{aligned}
& a_{+}=21.1 \mathrm{ft} / \mathrm{s}^{2} \\
& a_{-}=3.75 \mathrm{ft} / \mathrm{s}^{2} \\
& \nu=28.1 \mathrm{ft} / \mathrm{s} \\
& v_{\mathrm{f}}=25.5 \mathrm{ft} / \mathrm{s} \\
& d_{\mathrm{L}}=13.8 \mathrm{ft} .
\end{aligned}
$$

You might notice that between 0.25 s and 1.25 s , the data points are consistently above the best fit. This is due to modeling the acceleration as constant when careful analysis of sprinters shows that the acceleration drops slowly with time. ${ }^{2-4}$

Figure 5 is the velocity versus time. The velocity values fluctuate due to the propagation of uncertainties from the position values. Therefore, little can be said about the validity of the kinematic model from the velocity other than the red line, which has the same shape as Fig. 1, is not inconsistent with the data.

## Lessons from the kinematic model

The kinematic model should have some insight into the best way to go about stealing bases. Since Eq. (6) is so intractable, one way to proceed is to find the sensitivity to each of the five parameters by differentiating the total time of Eq. (6) with respect to each one,

$$
\begin{align*}
\frac{\partial T}{\partial a_{+}} & =-\frac{v}{2 a_{+}^{2}} \Rightarrow \Delta T=-\frac{v}{2 a_{+}} \frac{\Delta a_{+}}{a_{+}}  \tag{7}\\
\frac{\partial T}{\partial a_{-}} & =-\frac{\left(v-v_{\mathrm{f}}\right)^{2}}{2 v a_{-}^{2}} \Rightarrow \Delta T=-\frac{\left(v-v_{\mathrm{f}}\right)^{2}}{2 v a_{-}} \frac{\Delta a_{-}}{a_{-}},  \tag{8}\\
\frac{\partial T}{\partial v} & =\frac{1}{v}\left(\frac{v}{2 a_{+}}-\frac{D-d_{\mathrm{L}}}{v}+\frac{v^{2}-v_{\mathrm{f}}^{2}}{2 a_{-} v}\right) \Rightarrow  \tag{9}\\
\Delta T & =\left(\frac{v}{2 a_{+}}-\frac{D-d_{\mathrm{L}}}{v}+\frac{v^{2}-v_{\mathrm{f}}^{2}}{2 a_{-} v}\right) \frac{\Delta v}{v}, \\
\frac{\partial T}{\partial v_{\mathrm{f}}} & =-\frac{\left(v-v_{\mathrm{f}}\right)}{v a_{-}}=-\frac{1}{v_{\mathrm{f}}} \frac{v_{\mathrm{f}}}{v a_{-}}\left(v-v_{\mathrm{f}}\right) \Rightarrow  \tag{10}\\
\Delta T & =-\frac{v_{\mathrm{f}}}{v a_{-}}\left(v-v_{\mathrm{f}}\right) \frac{\Delta v_{\mathrm{f}}}{v_{\mathrm{f}}},
\end{align*}
$$

and $\frac{\partial T}{\partial d_{\mathrm{L}}}=-\frac{1}{v} \Rightarrow \Delta T=-\frac{d_{\mathrm{L}}}{v} \frac{\Delta d_{\mathrm{L}}}{d_{\mathrm{L}}}$.
These equations can be made a bit more helpful by plugging in the fitted values of the parameters to get a sense of the size of each contribution. The results are

$$
\begin{align*}
\Delta T & =-(0.67 \mathrm{~s}) \frac{\Delta a_{+}}{a_{+}}  \tag{12}\\
\Delta T & =-(0.032 \mathrm{~s}) \frac{\Delta a_{-}}{a_{-}}  \tag{13}\\
\Delta T & =-(1.4 \mathrm{~s}) \frac{\Delta v}{v}  \tag{14}\\
\Delta T & =-(0.63) \frac{\Delta v_{\mathrm{f}}}{v_{\mathrm{f}}} \tag{15}
\end{align*}
$$

$$
\begin{equation*}
\text { and } \Delta T=-(0.49 \mathrm{~s}) \frac{\Delta d_{\mathrm{L}}}{d_{\mathrm{L}}} \tag{16}
\end{equation*}
$$

Fractional changes in top speed shorten the time the most, followed by the acceleration during the jump, the final speed at second base, the size of the lead off, and finally the deceleration rate near second base, which is essentially insignificant.

I believe most baseball people would agree that the two biggest keys to success are the top speed of the runner and the acceleration away from first base. This explains why only the fleetest of foot even attempt to steal a base.

Some would disagree with the conclusion that the speed of arrival at second base is more important than the distance of the lead off. Yet, the author has noticed that nowadays many base stealers try to over-slide the base intentionally. They use the base itself to stop by grabbing it with a hand or a foot on the way, thus maintaining the highest possible speed when initially touching second base. So, perhaps this result is consistent with the behavior of professional ballplayers.

The speed upon reaching second base is only slightly more important than the lead-off distance. Announcers often focus heavily on the size of the lead, giving the impression that it is of central importance. According to this model, a big lead off might indicate that a steal will be attempted, but it is not the most important factor in determining success.

## References

1. For a fun three-minute video on the science behind stolen bases, check out ESPN Sport Science at www.youtube.com/ watch?v=xgz5-XToJIw\&feature=related.
2. O. Helene and M. T. Yamashita, "The force, power, and energy of the 100 meter sprint," Am. J. Phys. 78, 307-309 (March 2010).
3. A. Heck and T. Ellermeijer, "Giving students the run of sprinting models," Am. J. Phys. 77, 1028-1038 (Nov. 2009).
4. G. Wagner, "The 100-meter dash: Theory and experiment," Phys. Teach. 36, 144-146 (March 1998).
5. Video available at MLB.com, mlb.mlb.com/video/play. jsp?content_id=4405607\&c_id=mlb.
6. Video available at YouTube, www.youtube.com/ watch? $\mathrm{v}=\mathrm{Sv} 3 \mathrm{VrnO} 5 \mathrm{rGk}$.

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## AAPT Response to Next Generation Science Standards, Draft 2

On January 28, 2013, the American Association of Physics Teachers (AAPT) convened a group of 14 experienced high school physics teachers and representatives from the American Association of Physics Teachers, the American Physical Society, the American Institute of Physics, the National Society of Black Physicists, and the American Institute of Research to consider and develop a response to the January 2013 draft of the Next Generation Science Standards (NGSS).

The group was disappointed with that draft of NGSS and found that significant editorial changes, if not a whole new formulation, will be needed before AAPT and the broader science community can support that document as the basis for national K-12 science education standards.

## Read the full Executive Summary at http://goo.gl/xYM5S

