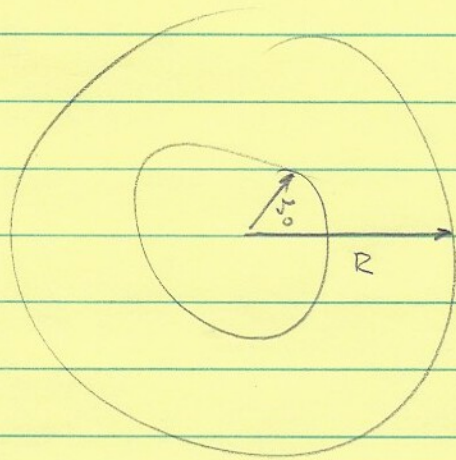


1.) #55 pg 332

a)



$$I = \int dm r^2 \quad \frac{dm}{M} = \frac{dA}{A} = \frac{2\pi r dr_0}{\pi(R^2 - r_0^2)} = \frac{dr_0^2}{R^2 - r_0^2}$$

$$I = \int_{r_0}^R M \frac{dr_0^2}{R^2 - r_0^2} r^2 = \frac{M}{R^2 - r_0^2} \int_{r_0}^R r^2 dr_0^2 = \frac{M}{2} \frac{R^4 - r_0^4}{R^2 - r_0^2}$$

$$I_{\text{cm}} = \frac{M}{2} (R^2 + r_0^2)$$

b) If $r_0 \rightarrow 0$ we recover $\frac{1}{2}MR^2$ ✓ solid disk
 If $r_0 \rightarrow R$ we recover MR^2 ✓ hoop.

$$c) \quad \frac{I}{I_{\text{tot}}} \alpha = \tau = MgR\epsilon\theta \rightarrow \frac{I}{I_{\text{tot}}} \alpha R = MgR^2\epsilon\theta$$

$$\text{so } a_{\text{cm}} = \alpha R = \frac{MR^2\epsilon\theta}{I_{\text{tot}}} g = \frac{MR^2}{M(R^2 + \frac{r_0^2}{2}) + MR^2} g\epsilon\theta$$

$$a_{\text{cm}} = \frac{g\epsilon\theta}{\frac{3}{2} + \frac{1}{2} \frac{r_0^2}{R^2}} = \frac{2g\epsilon\theta}{3 + (\frac{1.5}{2})^2} = .561 g\epsilon\theta$$

$$v_f^2 - v_i^2 = 2a_{\text{cm}}(.5\text{m}) \quad \text{so } \frac{v_f^2}{f} = 2a_{\text{cm}}(.5)$$

cont. 1.) for frictionless slide

$$v_{f_0}^2 = 2 g \sin(20^\circ) (1.5) \quad \text{so ...}$$

rolling

$$v_{fr}^2 = 2 (0.561 g \sin(20^\circ)) (1.5 \text{ m}) \Rightarrow v_f = 1.37 \frac{\text{m}}{\text{s}}$$

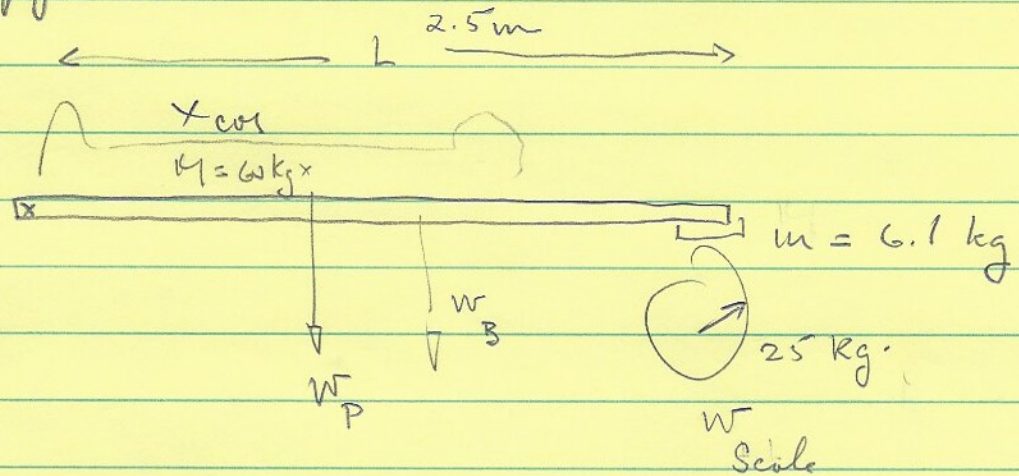
sliding

$$v_{f_0}^2 = 2 (g \sin(20^\circ)) (1.5 \text{ m})$$

$$\frac{v_{fr}}{v_{f_0}} = \sqrt{0.561} = 0.749$$

2.) # 57

pp 338



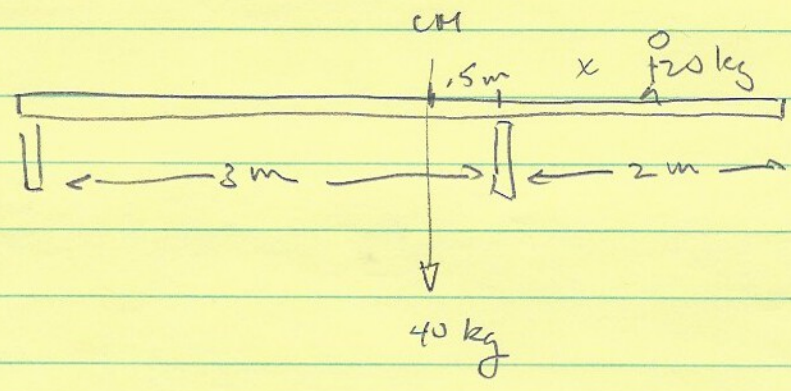
$$W_P X_{CM} + W_B \frac{L}{2} = W_{Scale} L$$

$$\frac{X_{CM}}{L} = \frac{-\frac{1}{2} W_B + W_{Scale}}{W_P} = \frac{-\frac{1}{2}(6.1) + 25}{60} \text{ kg}$$

$$\frac{X_{CM}}{2.5} = .3658 \quad \text{so} \quad X_{CM} = .9146\text{ m}$$

Set 12 Knight Chap 12

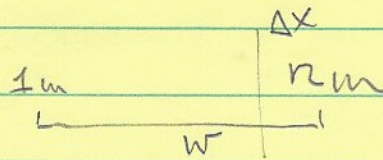
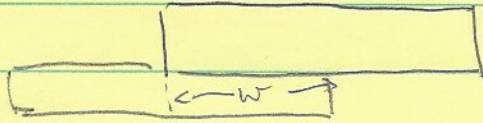
3.) # 60



$$(40 \text{ kg})(1.5) = (20 \text{ kg}) x_c$$

$$1 \text{ m} = x_c$$

4) #61



$$\text{or } \Delta x = \frac{1}{n+1} w$$

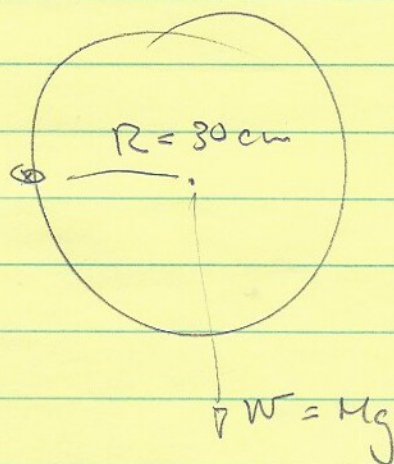
for us, $w = \frac{L}{2}$ use four bricks

$$\text{total distance} = \frac{L}{2} \left\{ 1 + \frac{1}{2} + \frac{1}{3} + \frac{1}{4} \right\}$$

$$= L \frac{25}{24} > L !$$

$$\sum_{n=1}^{\infty} \frac{1}{n} = \infty ! \quad \text{No limit !}$$

5.) # 72 pp 334



$$\tau = I_{\text{tot}} \alpha$$

$$MgR = \left(\frac{1}{2}MR^2 + MR^2\right) \alpha$$

$$\alpha_{\text{init}} = \frac{2}{3} \frac{g}{R}$$

$$\bar{U}_{\text{lost}} = MgR$$

$$\Delta U = \Delta KE$$

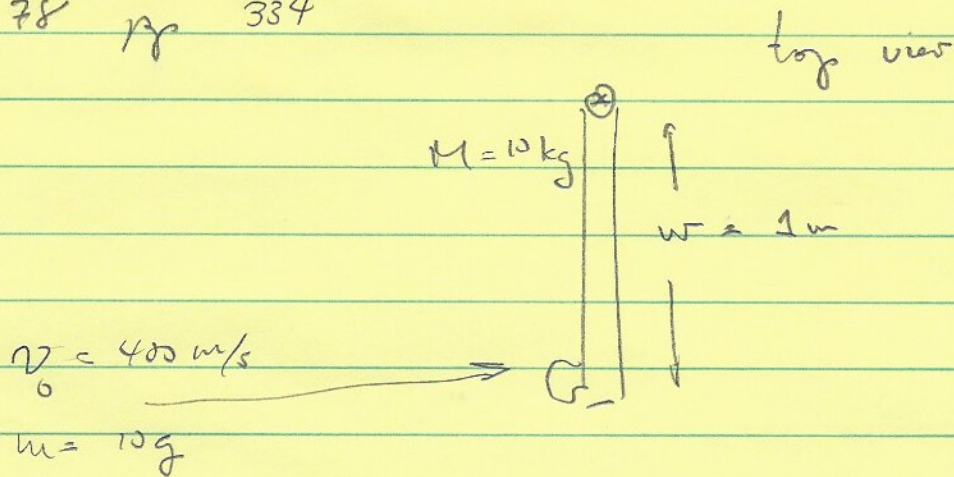
$$KE_{\text{gained}} = \frac{1}{2} I \omega_f^2 = \frac{1}{2} \left(\frac{3}{2} MR^2\right) \omega^2$$

$$\text{So } \frac{3}{4} R^2 \omega^2 = gR$$

$$\omega_f^2 = \frac{4}{3} \frac{g}{R}$$

$$\omega_f = \sqrt{\frac{4}{3} \frac{9.8}{.3}} = 6.6 \text{ rad/sec.}$$

6) # 78 pp 334



$$L_{in} = m v_0 l$$

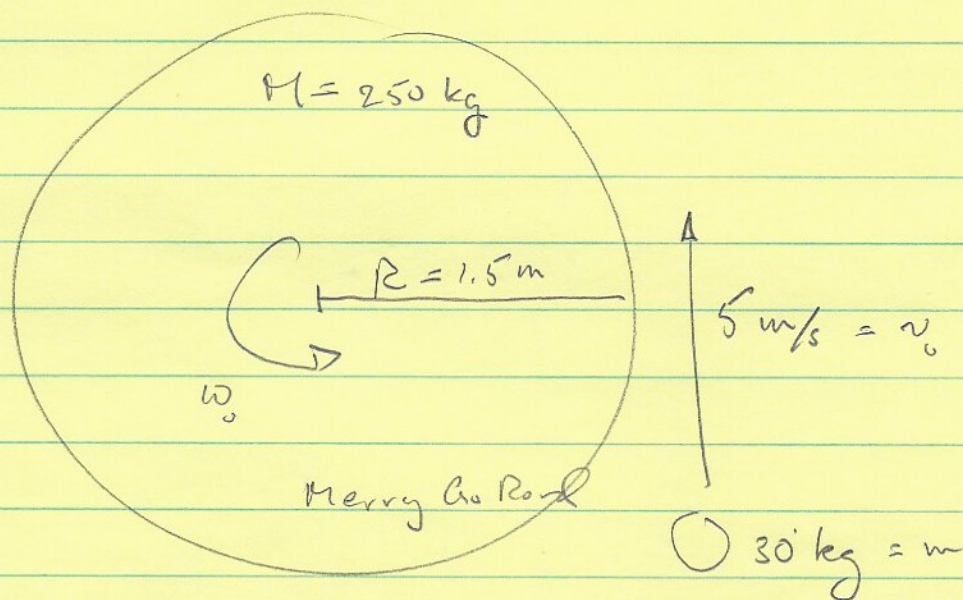
$$L_{out} = \bar{I}_{tot} \omega = \left(\frac{1}{3} M l^2 + m l^2 \right) \omega$$

$$\text{So! } m v_0 l = \left(\frac{1}{3} M + m \right) l^2 \omega$$

$$\Rightarrow \frac{m}{\left(\frac{1}{3} M + m \right)} \frac{v_0}{l} = \omega_{inf}$$

$$\omega_{inf} = \frac{3(.01)}{10.03} \frac{4 \times 10^2}{1 \text{ m}} = 1.196 \text{ rad/sec.}$$

7.) #81 nr 334



$$\omega = 2\pi \frac{(20)}{60 \text{ sec}} \text{ rad} = \frac{2\pi}{3} \text{ rad/sec}$$

Cons. of angular momentum!

$$L_f = L_{\text{MGR}} + L_{\text{John}}$$

$$\bar{I}_{\text{tot}} \omega_f = \bar{I}_{\text{MGR}} \omega_0 + m v_0 R$$

$$\omega_f = \frac{\bar{I}_{\text{MGR}} \omega_0 + m v_0 R}{\bar{I}_{\text{MGR}} + m R^2}$$

$$\bar{I}_{\text{MGR}} = \frac{1}{2} M R^2$$

7.) cont.

$$\text{So! } \omega_f = \frac{\omega_0 + \frac{m v_0 R}{\frac{1}{2} M R^2}}{1 + \frac{m R^2}{\frac{1}{2} M R^2}}$$

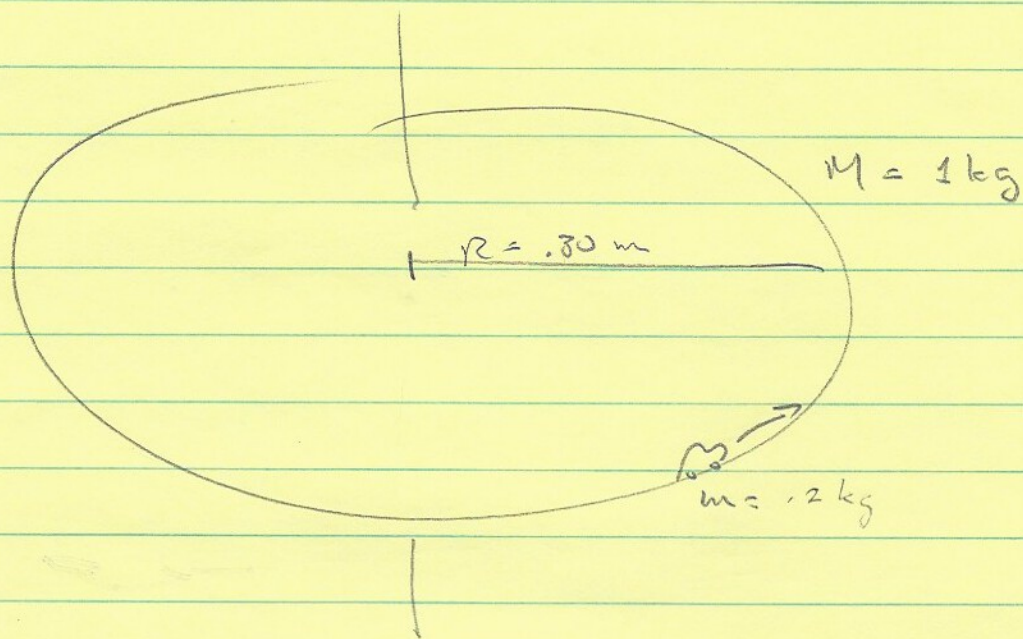
$$= \frac{\omega_0 + \frac{2m}{M} \frac{v_0}{R}}{1 + \frac{2m}{M}}$$

$$= \frac{\frac{2\pi}{3} + \frac{60}{250} \frac{5}{1.5}}{1 + \frac{60}{250}} = \frac{\frac{2\pi}{3} + \frac{4}{5}}{1 + \frac{6}{25}} = 2.334 \frac{\text{rad}}{\text{sec}}$$

$$\frac{\text{rad}}{\text{sec}} = \frac{1}{2\pi} \frac{\text{rev}}{\frac{1}{60} \text{ min}} = \frac{60}{2\pi} \frac{\text{rev}}{\text{min}} = \frac{30}{\pi} \frac{\text{rev}}{\text{min}}$$

Ans. 22.29' rev/min

8.) #88 p. 335



No Angular momentum! $L_{\text{car}} + L_{\text{track}} = 0$

$$\left. \begin{aligned} L_{\text{car}} &= m v_c R \\ L_{\text{track}} &= I \omega_t \end{aligned} \right\} \text{but } I \omega_t = -m v_c R$$

$$I = MR^2$$

We are told $v_c - \omega_t R = .75 \text{ m/s}$

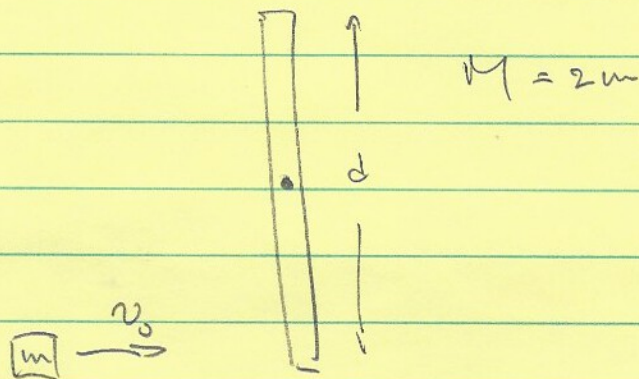
$$\Rightarrow v_c = -\frac{I \omega_t}{mR} \Rightarrow -\frac{I \omega_t}{mR} - \omega_t R = .75 \text{ m/s}$$

$$\omega_t \left(\frac{I}{mR} + R \right) = -.75 \text{ m/s}$$

$$\omega_t = \frac{(-.75 \text{ m/s}) / R}{\frac{M}{m} + 1} = -.416 \text{ rad/sec}$$

$$= -3.98 \text{ rev/min}$$

9.) # 89 pp 335



- ✓ Angular momentum is conserved
- ✓ KE. is preserved.

$$L_{m_i} = L_{m_f} + L_{R_f}$$

$$\frac{L_{m_i}^2}{2I_m} = \frac{L_{m_f}^2}{2I_m} + \frac{L_{R_f}^2}{2I_R}$$

So! $\frac{1}{2I_m} (L_{m_i}^2 - L_{m_f}^2) = \frac{1}{2I_R} L_{R_f}^2$ divide!

$$(L_{m_i} - L_{m_f}) = L_{R_f}$$

$$\frac{1}{2I_m} (L_{m_i} + L_{m_f}) = \frac{1}{2I_R} L_{R_f}$$

$$\begin{cases} L_{m_i} + L_{m_f} = \frac{I_m}{I_R} L_{R_f} \\ L_{m_i} - L_{m_f} = L_{R_f} \end{cases}$$

$$2 L_{m_c} = \left(1 + \frac{I_m}{I_R}\right) L_{R_f}$$

or

$$\frac{2}{1 + \frac{I_m}{I_R}} L_{m_c} = L_{R_f}$$

or

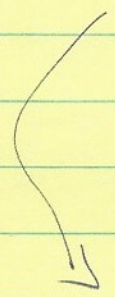
$$2 L_{m_f} = \left(\frac{I_m}{I_R} - 1\right) L_{R_f}$$

$$\cancel{2} L_{m_f} = \cancel{2} \frac{\left(\frac{I_m}{I_R} - 1\right)}{\left(\frac{I_m}{I_R} + 1\right)} L_{m_c}$$

So!

$$L_{R_f} = \frac{2}{1 + \frac{I_m}{I_R}} L_{m_c}$$

$$L_{m_f} = \frac{\left(\frac{I_m}{I_R} - 1\right)}{\left(\frac{I_m}{I_R} + 1\right)} L_{m_c}$$



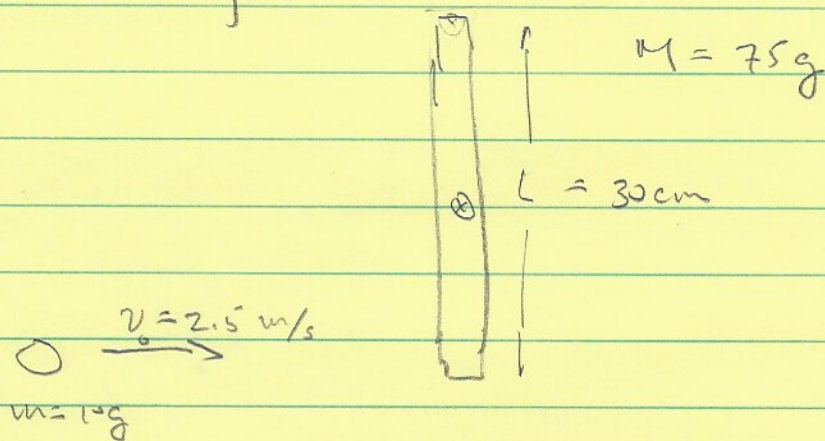
$$\frac{I_m}{I_R} = \frac{m \left(\frac{d}{2}\right)^2}{\frac{1}{12} 2m d^2} = \frac{12}{8} = \frac{3}{2}$$

$$v_f = \frac{\frac{3}{2} - 1}{\frac{3}{2} + 1} v_c = \frac{\frac{1}{2}}{\frac{5}{2}} = \frac{1}{5} v_c$$

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10.) #90 pp 335

Before



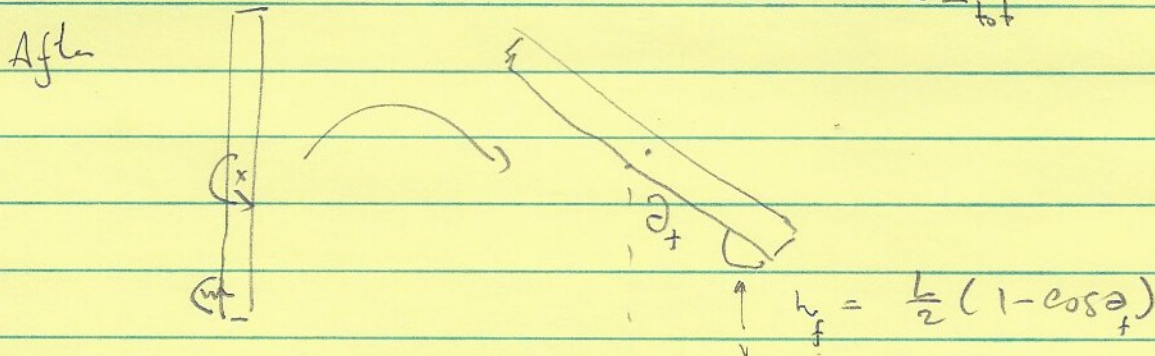
Physics?

$$L_{in} = L_{out} \quad \leadsto \quad m v_0 \frac{L}{2} = I_{tot} \omega$$

$$I_{tot} = I_{rod} + m \left(\frac{L}{2}\right)^2 = \frac{1}{12} M L^2 + \frac{1}{4} m L^2$$

just following the collision ...

$$\text{total kinetic energy out} = \frac{L_{out}^2}{2 I_{tot}} = \frac{L_{in}^2}{2 I_{tot}}$$



$$(KE)_i \leadsto (PE)_f \quad \text{so} \quad \frac{L_{out}^2}{2 I_{tot}} = mg \frac{L}{2} (1 - \cos \theta_f)$$

$$\text{so!} \quad \frac{\left(m v_0 \frac{L}{2}\right)^2}{2 \left(\frac{1}{12} M L^2 + \frac{1}{4} m L^2\right)} = mg \frac{L}{2} (1 - \cos \theta_f)$$

Set 12

Knight

cont. 10.)

$$\frac{v_0^2}{gL} = 1 - \cos \theta_f$$
$$4 \left(\frac{1}{12} \frac{M}{m} + \frac{1}{4} \right)$$

$$\cos \theta_f = 1 - \frac{v_0^2/gL}{\frac{1}{3} \frac{M}{m} + 1}$$

$$= 1 - \frac{(2.5)^2 / (9.8)(.3)}{\frac{1}{3} \left(\frac{75}{10} \right) + 1}$$

$$= 1 - .607 = .3926 \Rightarrow \theta_f = 66.88^\circ$$